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Fine Controls have been supplying process controls & instrumentation equipment since 1994, & now serves an ever expanding customer base, both in the UK & globally.

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Digital electropneumatic Process Controller

- Compact metal housing
- Graphic display with backlight
- Easy start-up of process controller and positioner
- Comprehensive range of additional software functions
- Profibus DPV1 (optional)
- Assembly acc. to IEC 534-6 / VDI VDE 3845

Type 8793 can be combined with...



Yoke type actuators



Rack/pinion actuators



Process control valve with remote Process Controller

The robust and compact process controller is designed to standardisation acc. to IEC 534-6 or VDI/VDE 3845 for assembly with linear and rotary actuators. In addition, the remote version can be combined with Bürkert process control valves. The digital electropneumatic SideControl process controller can be operated by the usual current and voltage standard signals and can also be equipped with the fieldbus interface PROFIBUS DPV1. Additional to the digital display the valve opening is signaled by a mechanical indicator element. The actual process value is directly supplied to the device as 4-20 mA, PT100 or as frequency signal. The process controller calculates the position setpoint for the subordinated positioner through the variance comparison. Due to the analogue feedback all analogue values on the controlling level can be transferred. The parameterization of process controller and positioner can be carried out automatically.

The easy handling and the selection of additional software functions are done either on a graphic display with backlight and keypad or via PC interface. Operation occurs via external operation and display module consisting of a backlit graphical display and a robust transparency keyboard with for keys with software driven function indication. For the user operation is very simple and clear, identical to the Bürkert positioner or process controller TopControl, type 8692/8693.

The pilot valve system can be used equally for single and double acting actuators. It is characterised by a defined safety feature in case of failure of the electrical or power supply and possesses an enormous air capacity range with pressure supply up to 7 bar.

| Technical data | |
|---|---|
| Material: Body Seal | Aluminium plastic-coated EPDM, NBR, FKM |
| Operating voltages | 24 VDC +/- 10% |
| Residual ripple | max. 10% |
| Setpoint setting | 0/4 to 20mA and 0 to 5/10 V |
| Input resistance | 0/4 to 20 mA: 180 Ω 0 to 5/10 V: 19 k Ω |
| Input data for actual value signal Setting 4 - 20 mA Frequency setting Setting Pt 100 | 180 Ω Input resistance / Resolution 12 bit 17 kΩ Input resistance, 0 - 1000 Hz / 1‰ o.R.. measuring range, Input signal > 300 mV88 Signal form Sine, rectangle, triangle Measuring range -20 - +220 °C, Resolution < 0.1 °C, M |
| Analogue feedback | 4-20 mA, 0-20 mA 0-10 V, 0-5 V |
| Binary input | galvanically isolated, 0-5 V = log "0", 10-30 V = log "1" |
| Binary Output Current limit | 2 Outputs (optional), galvanically isolated 100 mA, Output will be synchronised when overloaded |
| Control medium Dust concentration Particle density Pressure condensation point Oil concentration | Neutral gases, air DIN ISO 8573-1 Class 5 (<40µm particle size) Class 5 (<10mg/m³) Class 3 (<-20°C) Class 5 (<25mg/m³) |
| Ambient temperature | 0 to +60° C |
| Pilot air ports | Threaded port G 1/4 |
| Supply pressure | 1.4 to 7 bar ¹⁾ |
| Air input filter | Exchangeable (aperture size ~0.1mm) |
| Pilot valve system Air capacity | Single and double-acting up to 150 l _N /min. 95 l _N /min (with 1.4 bar ²⁾) for aeration and ventilation 150 l _N /min (with 6 bar ²⁾) for aeration and ventilation (QNn = 100 lN/min (acc. to the definition with decrease in pressure from 7 to 6 bar absolute) |
| Position detection module | Potentiometer, max. angle 180° |

continued on next page

¹⁾ The supply pressure has to be 0.5-1 bar above the minimum required pilot pressure for the valve actuator
²⁾ Pressure specifications: Overpressure with respect to atmospheric pressure

Technical data, continued





| Technical data | |
|-----------------------------|--|
| Stroke range valve spindle | Min. 30° on the rotary shaft, independent of lever |
| Installation | As required, display above or sideways |
| Type of protection | IP 65/67 acc. to EN 60529 (NEMA4x in preparation) |
| Power consumption | < 5 W |
| Electrical connection | |
| Multi-pin connection | M12, 8-pin / 4-pin; M8, 4-pin |
| Cable gland | 2xM20x1.5 (cable-Ø10mm) on screw terminals (0.14-1.5 mm ²) |
| Remote Version | 1xM12x1.5 (cable Ø3 to 6,5mm) |
| Bus communication | Profibus DPV1 (optional) |
| Inductive proximity switch | on request |
| Protection class | 3 acc. to VDE 0580 |
| Type of ignition protection | II 3 G nA II B T4 (in preparation) II 3 D tD A22 T135° (in preparation) |
| Conformity | EMV2004/108/EG |
| Approvals | CSA (in preparation) |

| Technical data - Position Sensor Remote | |
|---|--|
| Type of protection | IP 65/67 acc. to EN 60529 (NEMA4x in preparation) |
| Electrical connection | |
| Length for connection cable | 10m |
| Cable gland | 1xM16x1,5 (cable Ø5-10mm) on terminal screws (0,14-1,5 mm ²) |
| Actual signal position | digital (RS485) |
| Ambient temperature | -25 to +80 V: |
| Protection class | 3 acc. to VDE 0580 |
| Type of ignition protection | II 3 G nA II B T4 (in preparation) II 3 D tD A22 T135° (in preparation) |
| Conformity | EMV2004/108/EG |
| Approvals | CSA (in preparation) |

Using a remote positioner the length of the control air pipes influences the dynamics and attainable accuracy of the position control loop. The length of the control air pipes therefore should be as short as possible.

Example for assembly variations of Process Controller SideControl

Process Controller SideControl Type 8793

| | | | |
|--|---|--|---|
|  Linear actuators IEC 534-6 |  Rotary actuators VDI/VDE 3845 Type 8805 + Type 8793 |  Control valve system Type 2300 + Type 8793 Remote Process Controller + Type 8798 Remote Position Sensor |  Control valve system Type 2702 + Type 8793 Remote Process Controller + Type 8798 Remote Position Sensor |
|--|---|--|---|

Assembly options

Standard Version

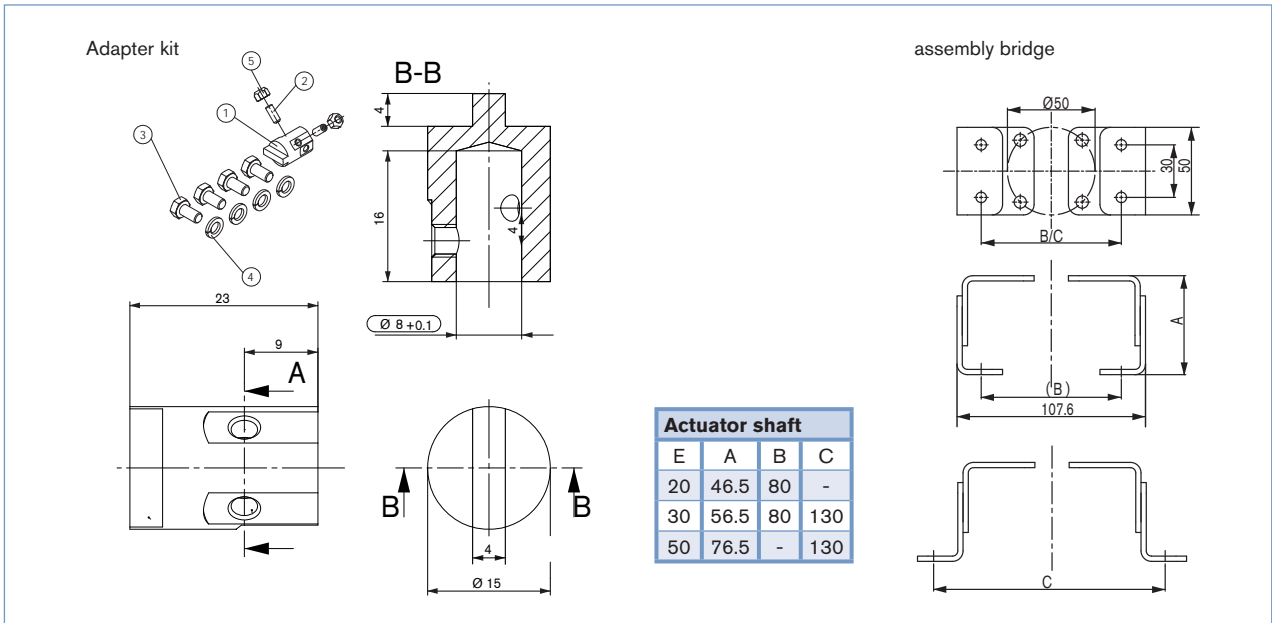
(Positioner with integrated position sensor, assembly acc. to NAMUR/IEC 534-6 and VDI/VDE 3845)

Assembly on rotary actuator



| | |
|--------------------------|---------|
| Item no. for adapter kit | 787 338 |
| Item no. assembly bridge | 770 294 |

Dimensions [mm]



Assembly on linear actuator



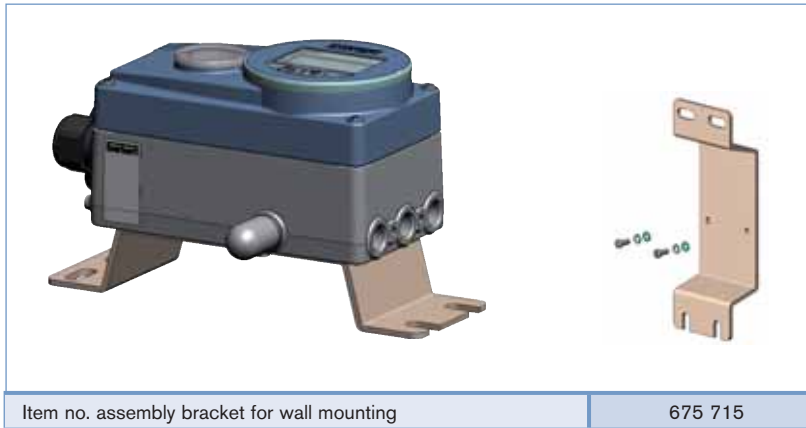
| | |
|--------------------------|---------|
| Item no. for adapter kit | 787 215 |
|--------------------------|---------|

Assembly options *continued*

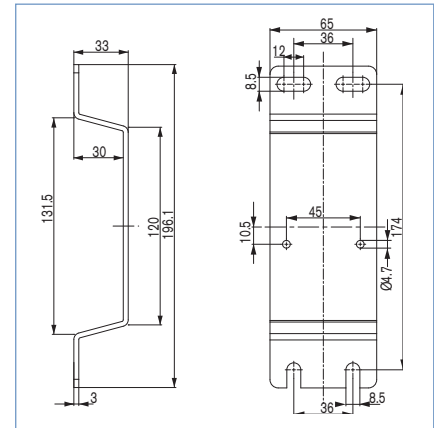
Remote Version

(Positioner remote from actuator with displacement positioner)

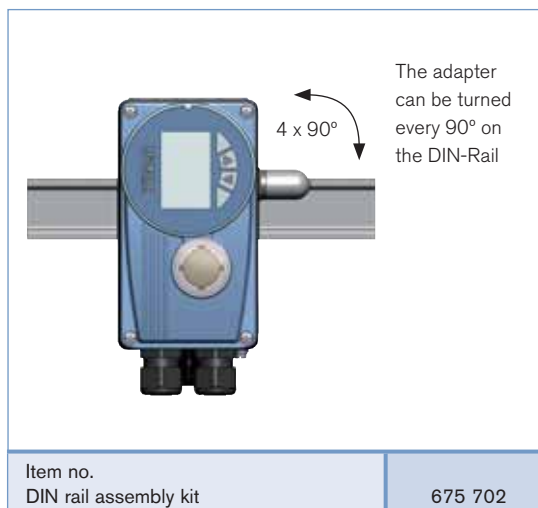
Assembly with accessory brackets



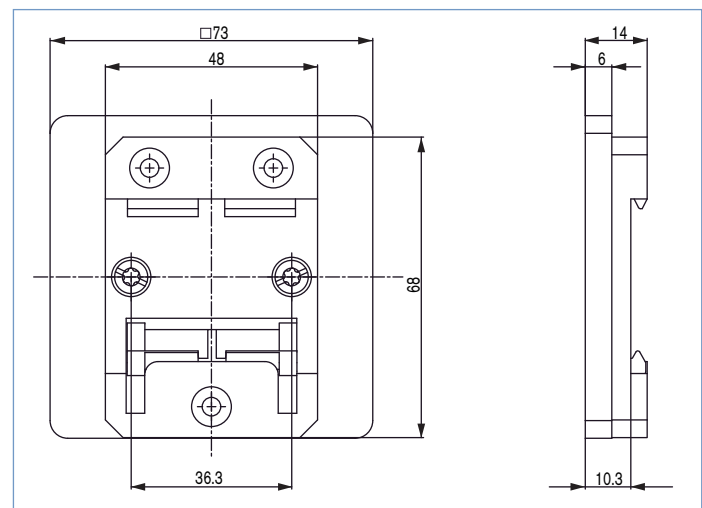
Dimensions [mm]



Assembly on DIN-Rail



Dimensions [mm]



Assembly options *continued*

Remote Version

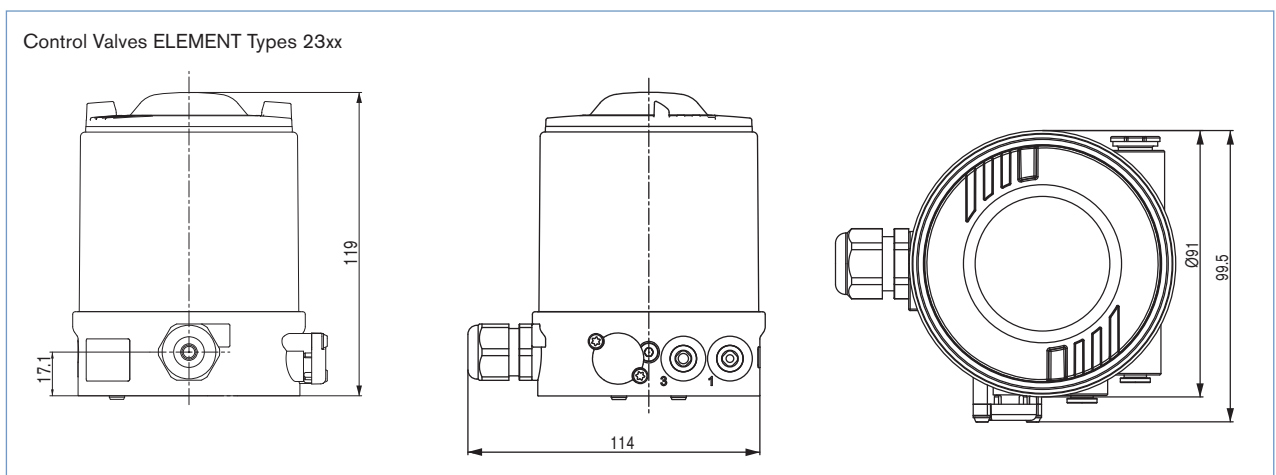
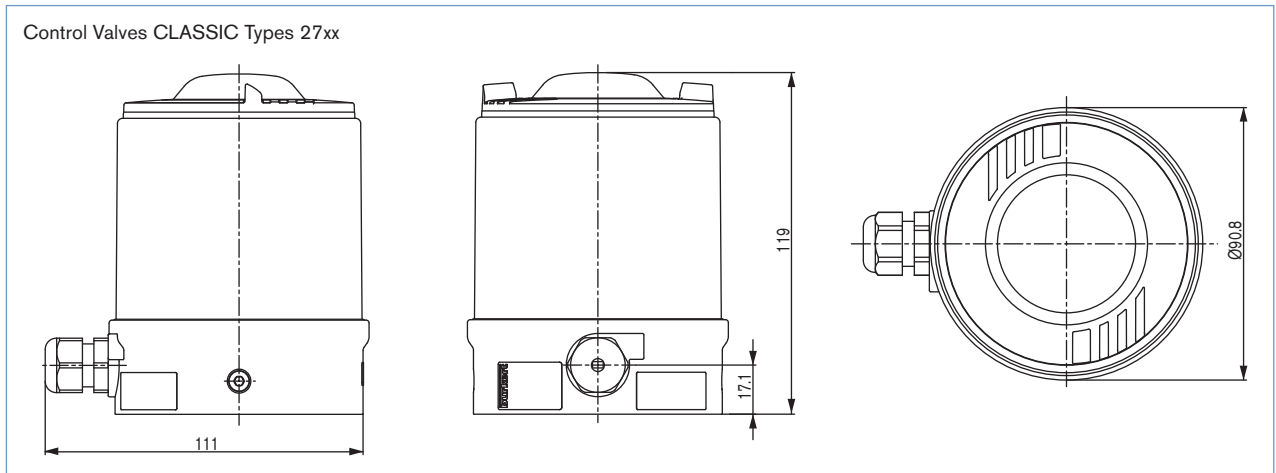
(Remote positioner from actuator with displacement positioner)

Type 8798



| | |
|----------------------------------|---------|
| Item no. | |
| Remote Position Sensor | |
| Control valves CLASSIC Type 27xx | 211 535 |
| Control valves ELEMENT Type 23xx | 212 360 |

Dimensions



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Ordering chart (other versions on request)

| Assembly variations | Communication | Electrical connection | Analogue feedback | 2 Binary outputs | Binary input | Initiator | Control function single and double-acting | Item no. |
|---------------------------------|---------------|-----------------------|-------------------|------------------|--------------|-----------|---|------------|
| NAMUR IEC 534-6 VDI/VDE 3845 | no | Cable gland | no | no | yes | no | yes | 206 593 |
| | | | no | no | yes | 2 | yes | on request |
| | | | no | yes | yes | no | yes | 206 595 |
| | | | yes | yes | yes | no | yes | 206 594 |
| | | | yes | yes | yes | 2 | yes | on request |
| | | Multi-pin | no | no | yes | no | yes | 206 596 |
| | | | no | no | yes | 2 | yes | on request |
| | | | no | yes | yes | no | yes | 206 599 |
| | | | yes | yes | yes | no | yes | 206 598 |
| | Profibus DPV1 | Multi-pin | yes | yes | yes | 2 | yes | on request |
| | | | via Bus | no | yes | no | yes | 206 600 |
| | | | via Bus | no | yes | 2 | yes | on request |
| | Remote | no | Cable gland | via Bus | yes | yes | no | yes |
| no | | | | no | yes | no | yes | 206 607 |
| no | | | | yes | yes | no | yes | 206 609 |
| | | | yes | yes | yes | no | yes | 206 608 |

i Further versions on request

- > Additional**
Remote Version (Positioner remote from actuator with displacement positioner sensor)
II 3 G nA II B T4
II 3 D tD A22 T135°
Initiators for end position feedback

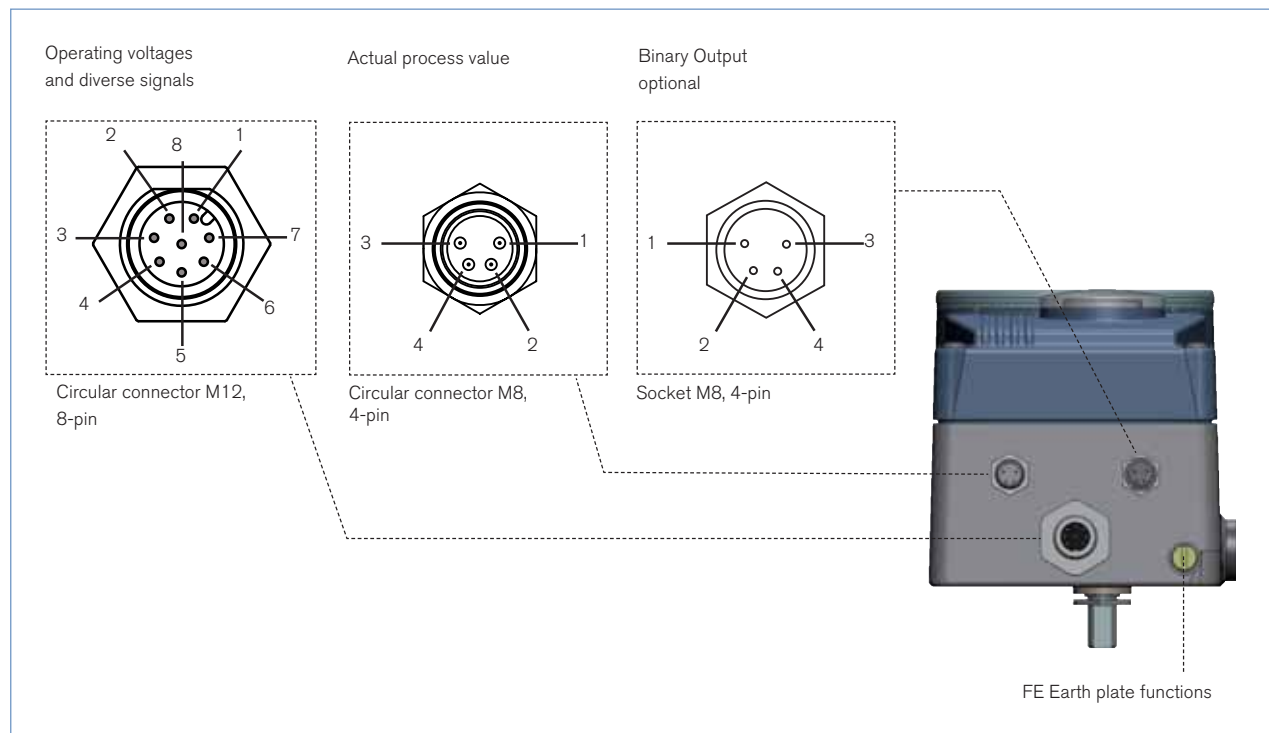
Ordering chart for accessories

| Description | Item no. |
|---|----------|
| Assembly bridge VDI/VDE 3845, Stainless steel | 770 294 |
| Adapter kit VDI/VDE 3845, Stainless steel | 787 338 |
| Adapter kit linear actuators IEC 534-6, stainless steel | 787 215 |
| Silencer G 1/4" (replacement part) | 780 780 |
| M12 socket, 8-pin, 2 m cable set | 919 061 |
| M8 plug, 4-pin for binary outputs, without cable | 917 131 |
| Accessories for Remote Version | |
| Bracket for wall mounting, Stainless steel | 675 715 |
| Holder for DIN-Rail assembly Al/Stainless steel | 675 702 |
| Remote position sensor control valves CLASSIC Type 27xx | 211 535 |
| Remote position sensor control valves CLASSIC Type 23xx | 212 360 |
| Adapter kit for remote position sensor control valves Type 23xx | 665 721 |
| Adapter kit for remote position sensor control valves Type 27xx | |
| Actuator size Ø80mm | 677 214 |
| Actuator size Ø100mm | 677 215 |
| Actuator size Ø125mm | 677 216 |
| Actuator size Ø175/Ø225mm | 677 217 |

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Connection options

Multi-pin connection



Circular connector M12 - 8-pin (Setpoint)

| Pin | Configuration | External Circuitry / level signal |
|-----|------------------------------------|---|
| 1 | Setpoint + (0/4-20 mA or 0-5/10 V) | 1 + (0/4-20 mA or 0-5/10 V) Completely galvanically separated |
| 2 | Setpoint GND | 2 GND |
| 3 | GND | 3 24 V DC ± 10% max. residual ripple 10% |
| 4 | + 24 V | 4 + |
| 5 | Binary input + | 5 + 0-5 V (log. 0) 10-30 V (log. 1) |
| 6 | Binary Output GND | 6 GND |

Optional analogue feedback

| | | |
|---|-----------------------|---|
| 8 | Analogue feedback + | 8 + (0/4-20 mA or 0-5/10 V) Completely galvanically separated |
| 7 | Analogue feedback GND | 7 GND |


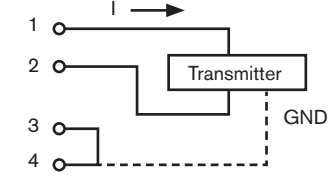

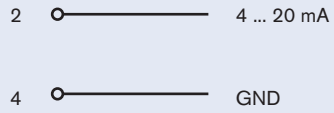

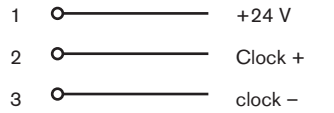

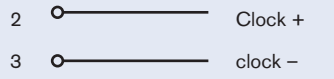

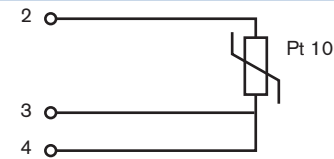
Socket M8, 4-pin (only with optional Binary Output)

| Pin | Configuration | External Circuitry / level signal |
|-----|-------------------|-----------------------------------|
| 1 | Binary output 1 | 1 0-24 V |
| 2 | Binary output 2 | 2 0-24 V |
| 3 | Binary Output GND | 3 GND |

Connection options

Multi-pin connection, *continued*

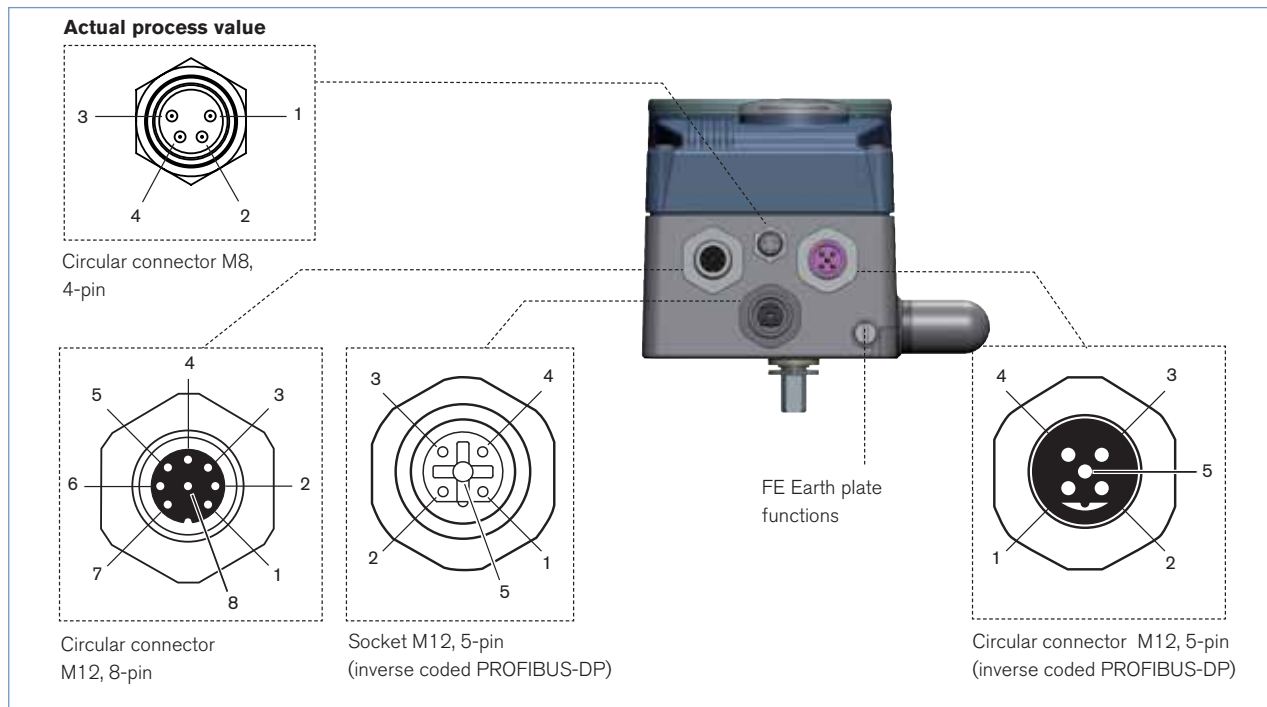
Plug assignments of the process actual value input (M8 circular plug)

| Input type* | Pin | Configuration | DIP switch | External Circuitry |
|--------------------------------------|------------------|--|---|---|
| 4 ... 20 mA - internally supplied | 1 2 3 4 | +24 V Transmitter supply Output from transmitter GND Bridge after GND (GND from 3-conductor transmitter) |  Switch on left |  |
| 4 ... 20 mA - externally supplied | 1 2 3 4 | Not used Process actual + Not used Process actual - |  Switch on right |  |
| Frequency - internally supplied | 1 2 3 4 | +24 V sensor supply Clock input + Clock input - (GND) Not used |  Switch on left |  |
| Frequency - externally supplied | 1 2 3 4 | Not used Clock input + Clock input - Not used |  Switch on right |  |
| Pt 100 (see note below) | 1 2 3 4 | Not used Process actual 1 (power supply) Process actual 3 (GND) Process actual 2 (compensation) |  Switch on right |  |

*adjustable through Software

Connection options, continued

PROFIBUS-DP connection



Operating voltages - Circular connector M12, 8-pin

| Pin | Configuration | External Circuitry / level signal |
|-----|-------------------------------------|---|
| 1 | Not used | |
| 2 | Not used | |
| 3 | GND | <p>24 V DC ± 10 % max. residual ripple 10 %</p> |
| 4 | +24 V | |
| 5 | Binary input + | |
| 6 | Binary input - | |
| 7 | Binary output 1 (oriented at Pin 3) | |
| 8 | Binary output 2 (oriented at Pin 3) | |

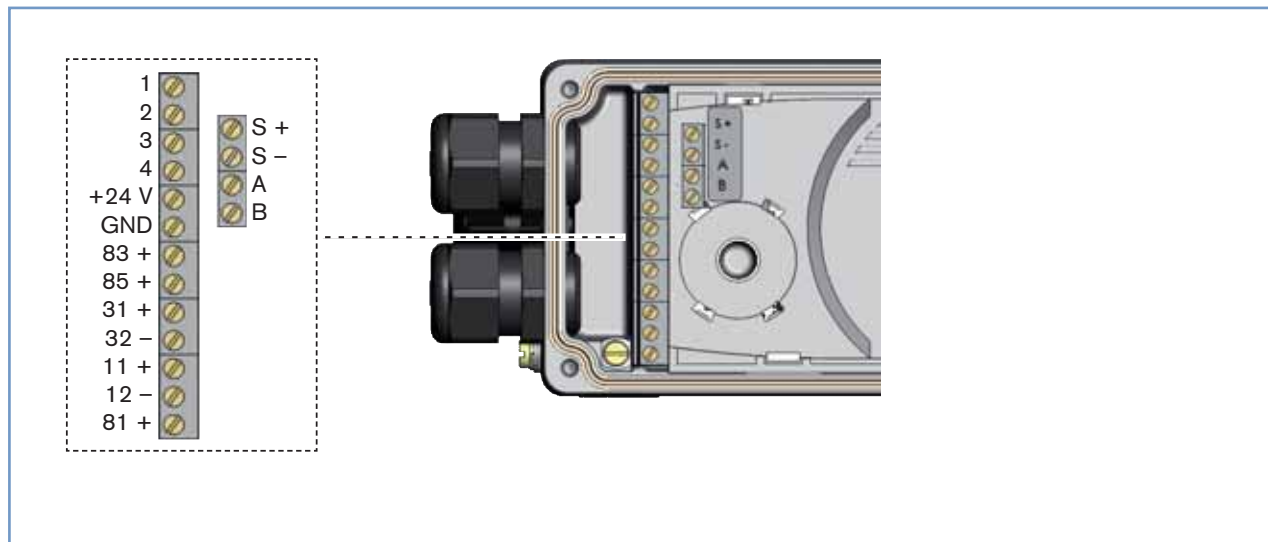
Bus-Connection - socket/Circular connector M12, 5-pin

| Pin | Configuration | External Circuitry / level signal |
|-----|---------------|--|
| 1 | VP+5 | Load resistance supply |
| 2 | RxD/TxD-N | Receive and send information -N, A Circuitry |
| 3 | DGND | Information transfer potential (measured to 5 V) |
| 4 | RxD/TxD-P | Receive and send information -N, A Circuitry |
| 5 | Shield | Shield / protective earth |

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Connection options, continued

Cable gland connection



| Terminal | Configuration | External Circuitry / level signal |
|----------|------------------------|--|
| 11 + | Setpoint + | 11 + + (0/4 ... 20 mA or 0 ... 5 / 10 V) Complete galvanic separation |
| 12 - | Setpoint GND | 12 - GND |
| 81 + | Binary input + | 81 + + 0 ... 5 V (log. 0) 10 ... 30 V (log. 1) Obtained at GND operating voltages (GND clamps) |
| +24 V | Operating voltages + | +24 V 24 V DC ± 10 % |
| GND | Operating voltages GND | GND Max. residual ripple 10 % |

Optional analogue feedback / Binary output

| Terminal | Configuration | External Circuitry / level signal |
|----------|-----------------------|---|
| 83 + | Binary output 1 | 83 + 24 V / 0 V, NC / NO obtained at GND operating voltages (GND clamps) |
| 85 + | Binary output 2 | 85 + 24 V / 0 V, NC / NO obtained at GND operating voltages (GND clamps) |
| 31 + | Analogue feedback + | 31 + + (0/4-20 mA or 0-5/10 V) completely galvanically isolated, |
| 32 - | Analogue feedback GND | 32 - GND |

Optional remote version in connection with remote position sensor, Type 8798

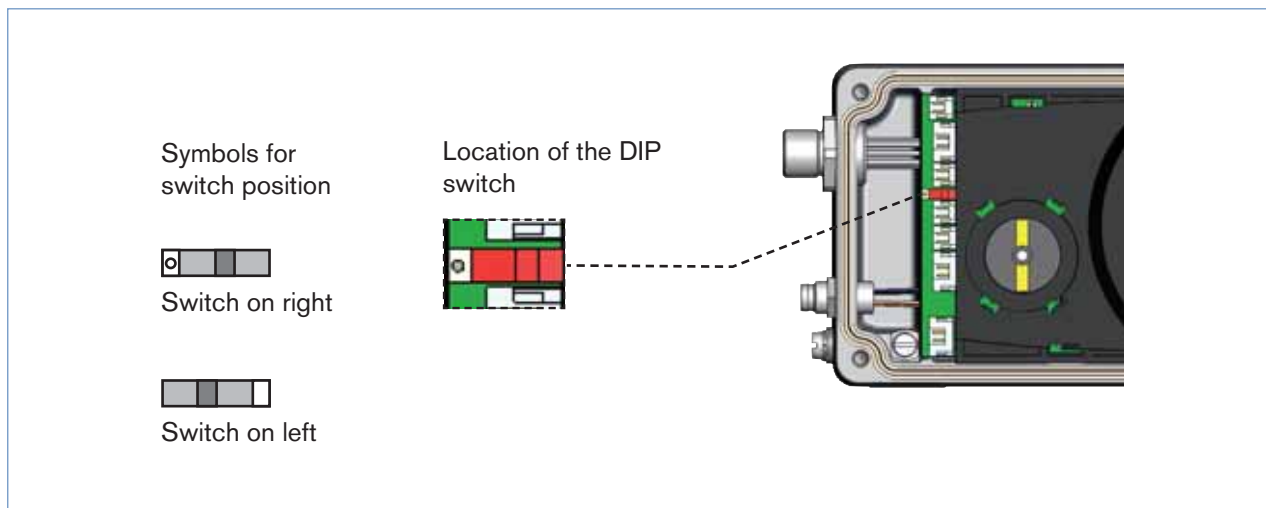
| Terminal | Configuration | External Circuitry |
|----------|-----------------------------|--------------------|
| S+ | Supply Sensor - | S+ |
| S- | Supply Sensor + | S- |
| A | Serial interface, B Cicutry | A A Cicutry |
| B | Serial interface, A Cicutry | B B Cicutry |

Remoter Sensor
Type 8798

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Connection options, continued

Cable gland connection

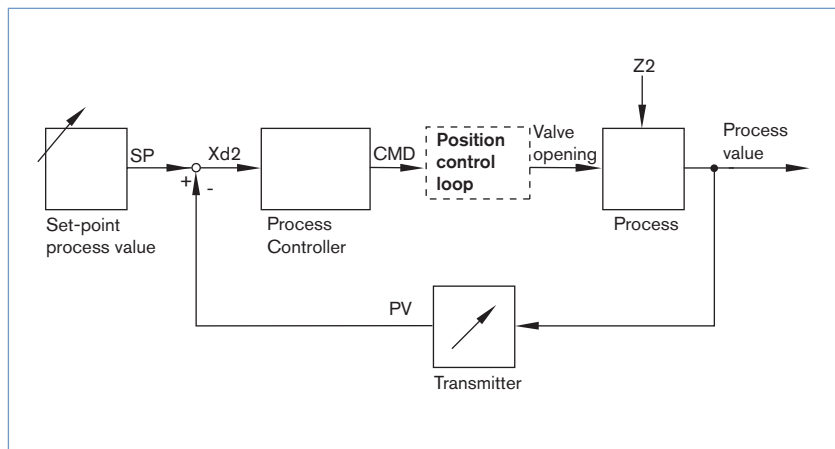


| Input type* | Terminal | Configuration | External Circuitry |
|--------------------------------------|----------------------|---|--------------------|
| 4 ... 20 mA - internally supplied | Actual process value | 1 +24 V transmitter input 2 Output from transmitter 3 Bridge after GND (GND from 3-conductor transmitter) 4 Not used | |
| | GND | GND | |
| Frequency - internally supplied | Actual process value | 1 +24 V sensor supply 2 Clock input + 3 Not used 4 Clock input - | |
| | GND | GND | |
| 4 ... 20 mA | Actual process value | 1 Not used 2 Process actual + 3 Process actual - 4 Not used | |
| Frequency - externally supplied | Actual process value | 1 Not used 2 Clock input + 3 Not used 4 Clock input - | |
| Pt 100 (see note below) | Actual process value | 1 Not used 2 Process actual 1 (power supply) 3 Process actual 3 (GND) 4 Process actual 2 (compensation) | |

*adjustable through Software

Signal flow plan

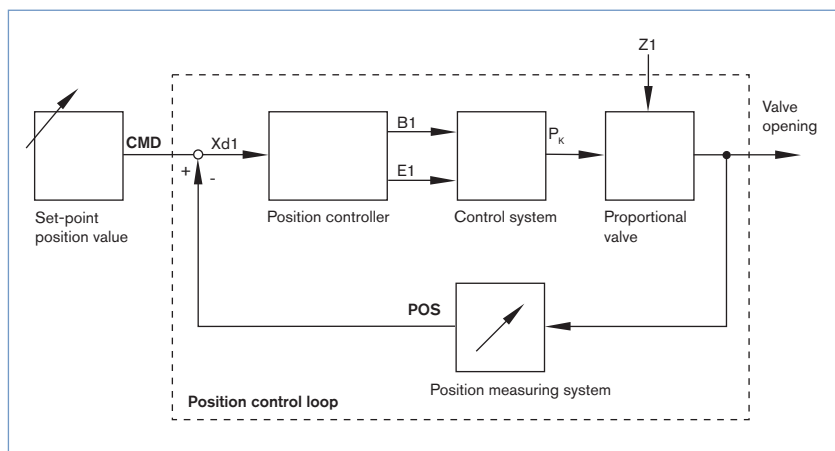
Process control loop



Additional software options of the process controller SideControl Type 8793 (extract)

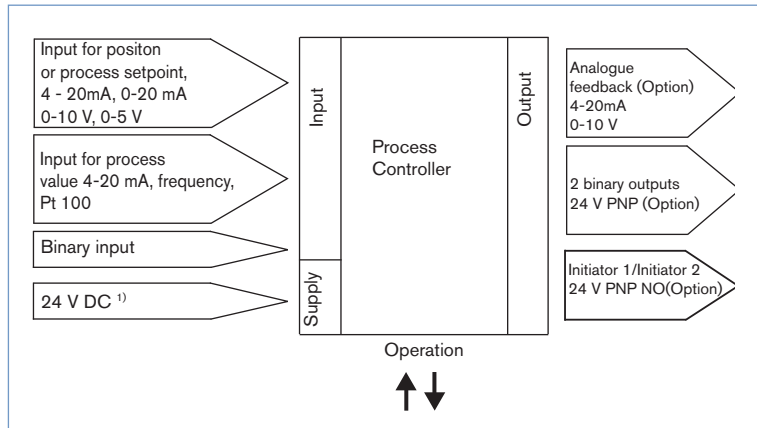
- Automatic start of the control system
- Automatic parameterisation of the process control loop
- Automatic or manual characteristics curves selection
- Setting of the seal and the maximum stroke threshold respectively
- Parameterisation of the Positioner
- Manual parameterisation of process controller
- Limitation of the stroke range
- Limitation of the manipulating speed
- Setting of the moving direction
- Configuration of the binary input
- Signal range splitting on several controllers
- Configuration of analogue or 2 binary outputs
- Signal fault detection
- Safety position
- Code protection
- Contrast inversion of the display
- Diagnostic functions

Position control loop

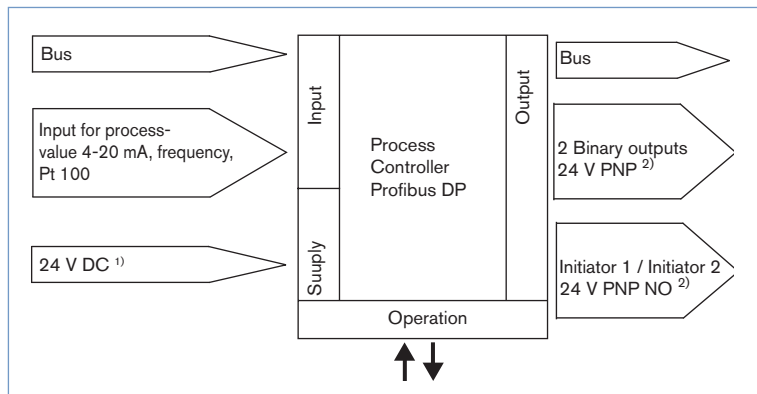


Schematic diagram of SideControl, Type 8793

without fieldbus interface



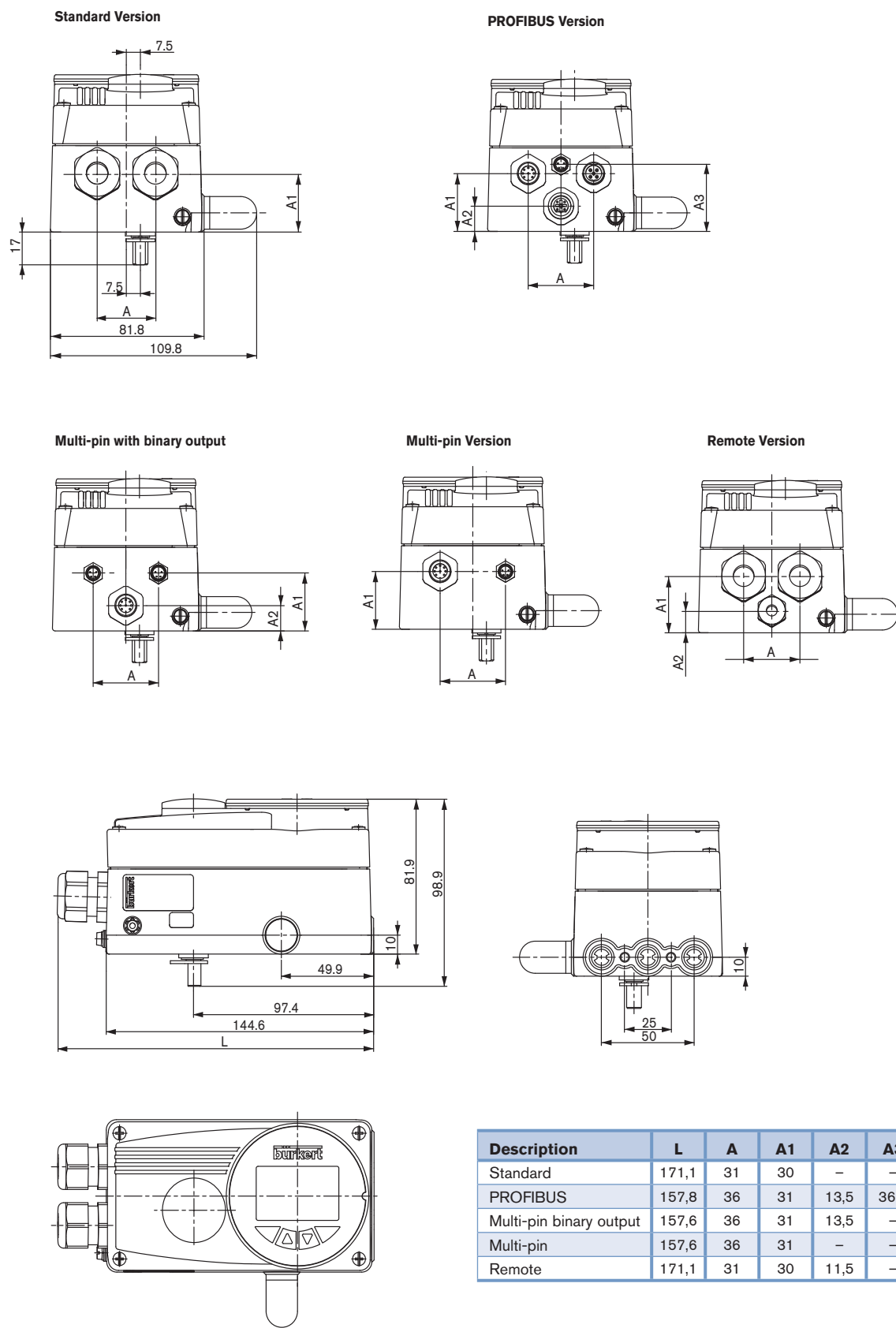
With Profibus DP



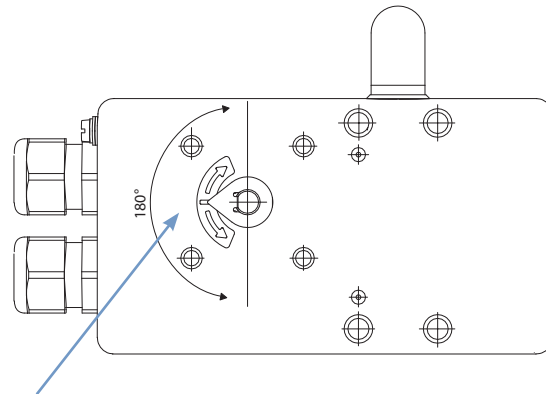
¹⁾ The operating voltage is supplied with a 3-wire unit independent from the setpoint signal

²⁾ Alternative options

Dimensions [mm]



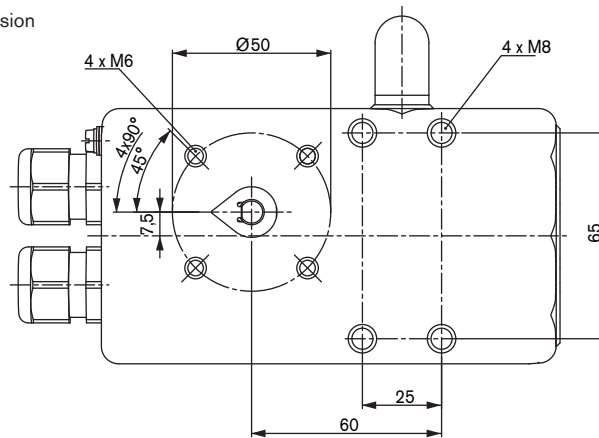
Dimensions [mm]



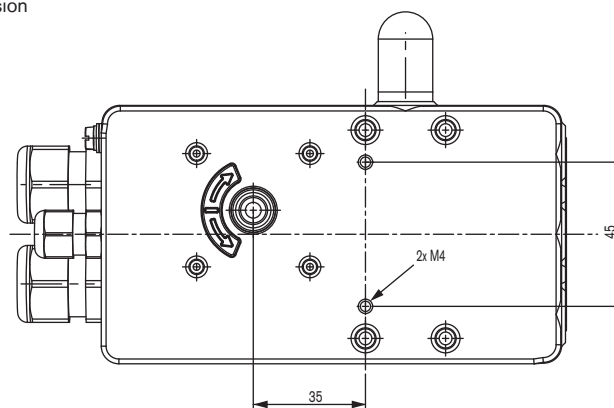
The rotation angle of the sensor must be within a range of 180°

With the valve open approx. 50%, the sensor indicator should be in this position.

Standard Version



Remote Version



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In case of special application conditions, please consult for advice

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